

# The overshoot problem in inflation after tunneling

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# Outline

Motivation

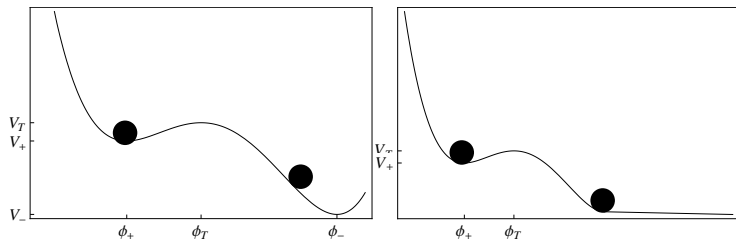
Setup

Monomials

Polynomials

Conclusions and Outlook

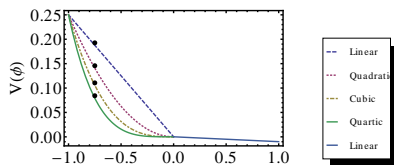
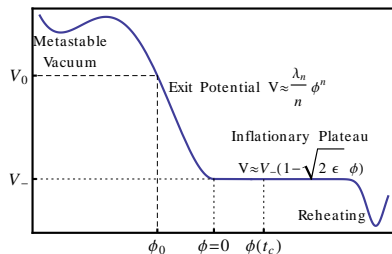
# Motivation



- ▶ large field models (detectable gravity waves)
- ▶ small field models (undetectable gravity waves)
- ▶ relative frequency of potentials of either shape
- ▶ populating the initial condition
- ▶ ignore measure problem
- ▶ best observations will be able to detect  $r \approx 0.01$
- ▶ Lyth bound  $\Delta\phi > \sqrt{r\Delta N}M_P$



# Setup

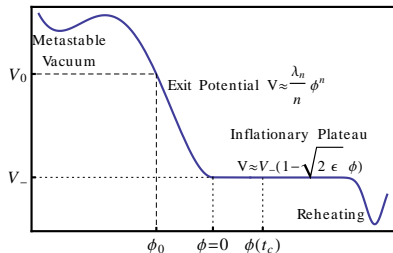


- ▶ tunnel from metastable vacuum to  $\phi_0$  on the “exit potential”
- ▶ roll down towards inflationary plateau (linear potential)

$$V = V_-(1 - \sqrt{2\epsilon}\phi)$$

- ▶ how far will the field go for  $\phi^n$  monomial exit potentials? (not far!)
- ▶ rather: how far until it reaches slow roll?

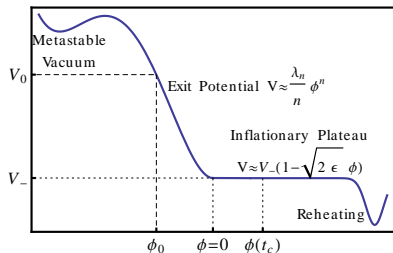
# Equation of Motion



$$\ddot{\phi} + \frac{3}{t}\dot{\phi} + \partial_{\phi}V = 0 \quad (1)$$

- ▶ open universe after tunneling
- ▶ assume curvature domination  $H = \frac{1}{t}$
- ▶ in general, difficult to solve

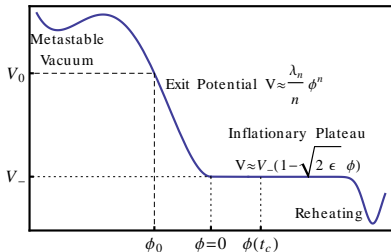
# Linear exit potential $V = V_-(1 - \lambda_1\phi)$



$$\ddot{\phi} + \frac{3}{t}\dot{\phi} - \lambda_1 V_- = 0 \quad (2)$$

- ▶ solved by  $\phi = \phi_0 + \frac{\lambda_1 V_-}{8} t^2$
- ▶ terminal velocity  $\dot{\phi}_f = \sqrt{-\frac{1}{2}\lambda_1 V_- \phi_0}$ .
- ▶ on the plateau, slow roll starts at  $\phi(t_c) = \frac{3}{2\sqrt{2}} \frac{\epsilon}{-} \phi_0$
- ▶ curvature domination for  $|\phi_0| < 1$

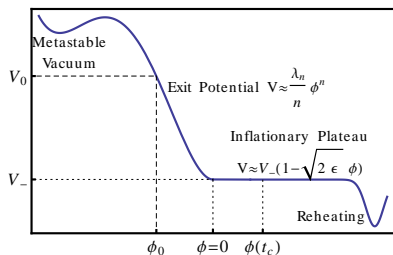
# Quadratic exit potential $V = V_- + \frac{1}{2}m^2\phi^2$



$$\ddot{\phi} + \frac{3}{t}\dot{\phi} + m^2\phi = 0 \quad (3)$$

- ▶ solved by  $\phi = 2\phi_0 \frac{J_1(mt)}{mt}$  (Bessel function)
- ▶ terminal velocity  $\dot{\phi}_f = \phi_0 \frac{J_0(mt_f) - J_1(mt_f)}{t_f} \approx -0.21 m\phi_0$ ,  $mt_f$  first zero of  $J_1$
- ▶ on the plateau, slow roll starts at  $\phi(t_c) = \frac{3}{2\sqrt{2}} \frac{\epsilon}{+} \phi_0 J_0(mt_f) \approx \frac{3}{2\sqrt{2}} \frac{\epsilon}{-} 0.403\phi_0$
- ▶ curvature domination for  $|\phi_0| < 1$  and  $V_- \ll V_0$

$$\text{Cubic exit potential } V = V_- - \frac{1}{3}\lambda_3\phi^3$$

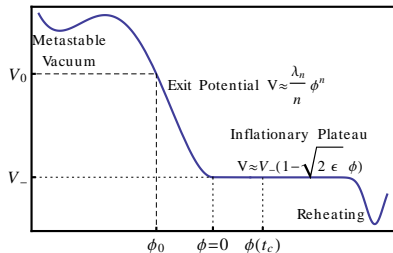


$$\ddot{\phi} + \frac{3}{t}\dot{\phi} - \lambda_3\phi^2 = 0 \quad (4)$$

- ▶ can't find solution
- ▶ BUT: can find solution for larger friction  $\frac{10}{3t}$  and  $\frac{5}{3t}$



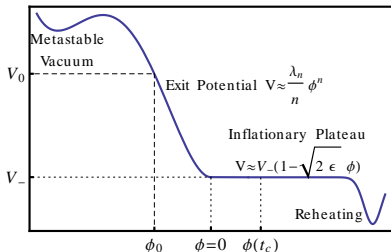
# Cubic exit potential $V = V_- - \frac{1}{3}\lambda_3\phi^3$ , larger friction



$$\ddot{\phi} + \frac{10}{3t} \dot{\phi} - \lambda_3 \phi^2 = 0 \quad (5)$$

- ▶ solved by  $\phi = -\frac{2}{3\lambda_3 t^2} [z(t)^2 p(z(t), 0, 1) + 1]$  with  $z(t) = (-42\lambda_3\phi_0 t^2)^{1/6}$  and elliptic Weierstrass function  $p$
- ▶ terminal velocity  $\dot{\phi}(t_f) \approx -0.03\phi_0 \sqrt{-\lambda_3\phi_0}$
- ▶ on the plateau, slow roll starts at  $\phi(t_c) = \frac{3}{4\sqrt{2}}\sqrt{\epsilon} - 0.1\phi_0$ .

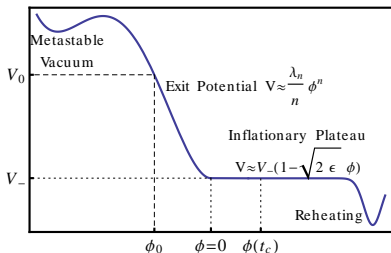
# Cubic exit potential $V = V_- - \frac{1}{3}\lambda_3\phi^3$ , smaller friction



$$\ddot{\phi} + \frac{5}{3t}\dot{\phi} - \lambda_3\phi^2 = 0 \quad (6)$$

- ▶ solved by  $\phi = (8/3\lambda_3 t^2)^{1/3} \text{p}((3t^2\lambda_3/8)^{1/3} + \zeta, 0, \xi)$  with  $\zeta = 2^{1/3} \frac{\Gamma(1/3)\Gamma(7/6)}{\sqrt{\pi}|\phi_0|^{1/3}}$ ,  $\xi = -\phi_0^2$  and elliptic Weierstrass function  $\text{p}$
- ▶ terminal velocity  $\dot{\phi}(t_f) \approx -0.174\phi_0\sqrt{-\lambda_3\phi_0}$
- ▶ on the plateau, slow roll starts at  $\phi(t_c) = \frac{3}{4\sqrt{2}}\sqrt{\epsilon} - \frac{1}{3}\phi_0$ .
- ▶ curvature dominates for  $|\phi_{hi}| < M_p$

# Cubic exit potential $V = V_- - \frac{1}{3}\lambda_3\phi^3$ , correct friction

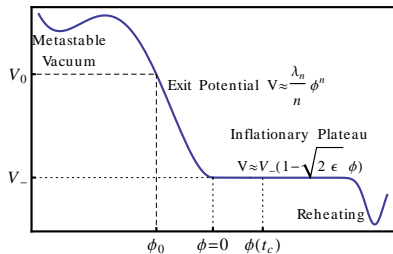


$$\ddot{\phi} + \frac{3}{t}\dot{\phi} - \lambda_3\phi^2 = 0 \quad (7)$$

- ▶ can't find solution
- ▶ for larger friction  $\frac{10}{3t}$ :  $\phi(t_c) = \frac{3}{4\sqrt{2}}\sqrt{\epsilon} - 0.1\phi_0$
- ▶ for smaller friction  $\frac{5}{3t}$ :  $\phi(t_c) = \frac{3}{4\sqrt{2}}\sqrt{\epsilon} - \frac{1}{3}\phi_0$
- ▶ true position when slow roll starts:

$$\frac{3}{4\sqrt{2}}\sqrt{\epsilon} - 0.1\phi_0 < \phi(t_c) < \frac{3}{4\sqrt{2}}\sqrt{\epsilon} - \frac{1}{3}\phi_0$$

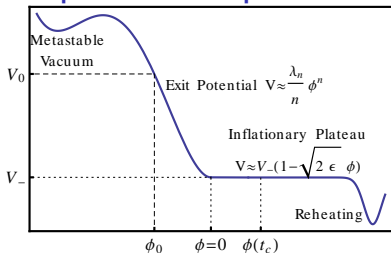
# Quartic exit potential $V = V_- + \frac{1}{4}\lambda_4\phi^4$



$$\ddot{\phi} + \frac{3}{t}\dot{\phi} + \lambda_4\phi^3 = 0 \quad (8)$$

- ▶ solved by  $\phi = \frac{8\phi_0}{8+t^2\lambda_4\phi_0^2}$
- ▶ terminal velocity  $\dot{\phi}_f = 0$ .
- ▶ on the plateau, slow roll starts at  $\phi(t_c) = \frac{3}{2\sqrt{2}}\frac{\epsilon}{-}\phi_0$
- ▶ curvature domination

# Higher power exit potential $V = V_- + \frac{1}{n}\lambda_n\phi^n, n > 4$



$$\ddot{\phi} + \frac{3}{t}\dot{\phi} + \lambda_n\phi^n = 0 \quad (9)$$

$$\ddot{\phi} + \frac{\gamma}{t}\dot{\phi} + \phi^n = 0 \quad (10)$$

- ▶ don't know how to solve
- ▶ BUT: know first integral for equation with smaller friction term  $\gamma = \frac{n+2}{n-2}$

$$C = \frac{t^{\gamma-1}}{2} \left( \dot{\phi}^2 t^2 + \dot{\phi}\phi t(\gamma - 1) \right) + \frac{1}{n} \left( \phi t^{\frac{\gamma-1}{2}} \right)^n$$

- ▶ at  $t = 0, \phi, \dot{\phi} < \infty \Rightarrow C = 0$
- ▶ at  $t = t_f, \phi(t_f) = 0 \Rightarrow \dot{\phi}(t_f) = 0$
- ▶ curvature domination

Polynomial exit potential  $V = (-1)^m \frac{\lambda_m}{m} \phi^m + (-1)^n \frac{\lambda_n}{n} \phi^n$

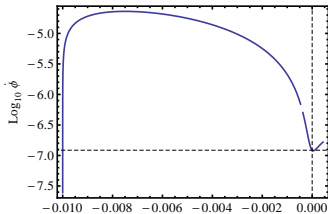
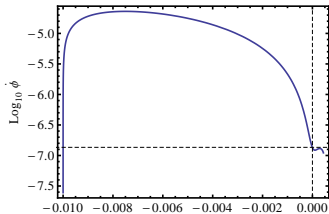
$$(-1)^m \lambda_m \phi^{m-1} (1 + \delta) \Big|_{\phi=\phi_*} = (-1)^n \lambda_n \phi^{n-1} \Big|_{\phi=\phi_*} \quad (11)$$

$$\frac{t_*}{t_*^{(0)}} = 1 + \frac{\phi_0}{6(\phi_*^{(0)} - \phi_0)} \delta, \quad \frac{\dot{\phi}_*}{\dot{\phi}_*^{(0)}} = 1 + \frac{\phi_0 - \frac{4}{3}\phi_*^{(0)}}{2(\phi_0 - \phi_*^{(0)})} \delta \quad (12)$$

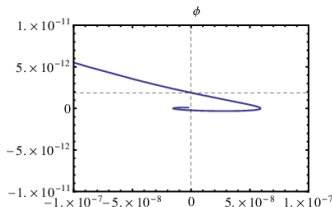
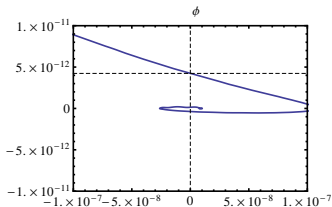
- ▶ assume  $m < n \leq 4$
- ▶ effective field theory:  $m, n \leq 4$ , otherwise suppressed ( $|\phi_0| < M_p$ )
- ▶ glue solutions for  $\phi^m, \phi^n$
- ▶ small perturbation of the matching location  $\Rightarrow$  small perturbation of  $\dot{\phi} \Rightarrow$  small change in initial conditions for second part of the potential



# Polynomial Examples



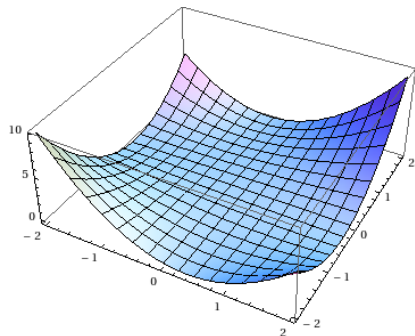
$$V_- - \lambda_1 \phi + \frac{\lambda_4}{4} \phi^4$$



$$V_- + \frac{1}{2} m^2 \phi^2 + \frac{\lambda_4}{4} \phi^4$$

overshoot controlled by lowest-order term

## Non-zero initial speed



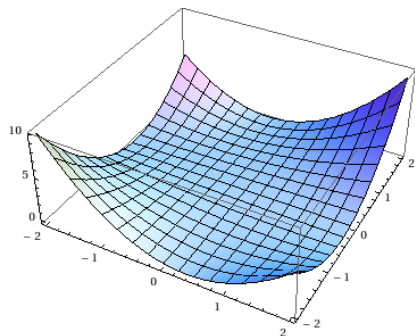
$$\ddot{\phi} = -\frac{3}{t}\dot{\phi} - \partial_{\phi} V \quad (13)$$

$$\Rightarrow \dot{\phi} = \dot{\phi}_{\epsilon} \left(\frac{\epsilon}{t}\right)^3 \quad (14)$$

- ▶ non-zero initial speed after tunneling
- ▶ possible in multi-field setups
- ▶ immediate slow-down



## Non-zero initial speed

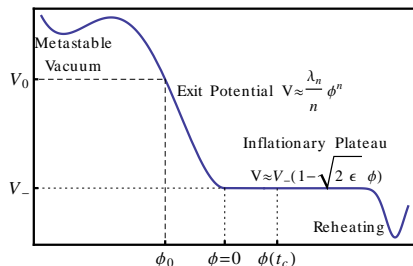


$$\ddot{\phi} = -\frac{3}{t}\dot{\phi} - \partial_{\phi} V \quad (15)$$

$$\Rightarrow \dot{\phi} = \dot{\phi}_{\epsilon} \left(\frac{\epsilon}{t}\right)^3 \quad (16)$$

- ▶ tunneling not directly into today's vacuum, but somewhere up the inflationary slope
- ▶ could have non-zero initial speed
- ▶ no overshoot problem either for effective single-field evolution

# Conclusions and Outlook



$$V = \frac{\lambda_n}{n} \phi^n$$

$$\Delta\phi = \frac{3}{4\sqrt{2}} \sqrt{\epsilon} + C|\phi_0|$$

$$C = \{1, 0.53, [0.33, 0.1]\}$$

- ▶ finite small overshoot for  $n = 1 \dots 3$
- ▶ no overshoot for  $n \geq 4$
- ▶ for polynomials, the lowest order term controls the overshoot